

① Vector field

$$M \ni p \xrightarrow{X} X_p \in T_p(M)$$

i.e. a vector field is an assignment to every point $p \in M$ of a vector X_p from $T_p(M)$.

$\mathcal{F}(M)$ - algebra of C^∞ functions on M

one can think about X as a map

$$X: \mathcal{F}(M) \longrightarrow \mathcal{F}(M)$$

$$f \longmapsto X(f) \quad \text{~~not } X_p(f) \text{ }~~$$

$$X(f)(p) = X_p(f)$$

X is of class C^k if $\forall f \in \mathcal{F}(M)$ $X(f)$ is of class C^k

locally $(U, x): X = X^\mu \frac{\partial}{\partial x^\mu}$ where $X^\mu: M \rightarrow \mathbb{R}$

if X is of class C^k then $X^\mu = X^\mu(p)$ are of class C^k and vice versa.

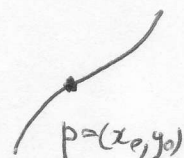
$\mathcal{X}(M)$ - vector space of vector fields of class C^∞ on M
(infinite dimensional!)

② Trajectory of a vector field passing through p
or integral curve of X passing through p

Ex $X = y\partial_x - x\partial_y$ vector field on $\mathbb{R}^2$

$$X^\mu = \begin{pmatrix} y \\ -x \end{pmatrix}$$

$$\gamma(t) = \begin{pmatrix} x \\ y \end{pmatrix}(t) \text{ s.t. } \frac{d\gamma^\mu}{dt} = X^\mu$$



$$\left. \begin{aligned} \frac{dx}{dt} &= y \\ \frac{dy}{dt} &= -x \end{aligned} \right\} \Rightarrow \left. \begin{aligned} \frac{d(x+iy)}{dt} &= -i(x+iy) \\ x+iy &= (x_0+iy_0)e^{-it} \end{aligned} \right\} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix}(t) = \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

$$\gamma^\mu(t) = \psi_t \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

$$\psi_t = \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \quad \psi_0 = \text{id} \quad \psi_{t+s} = \psi_t \circ \psi_s$$

Ex $X = \partial_y - x^{-2} \partial_x$ on $\mathbb{R}_+ \setminus \{0\}$

$$\left. \begin{aligned} \frac{dx}{dt} &= x^2 \\ \frac{dy}{dt} &= -x^{-2} \end{aligned} \right\} \Rightarrow \begin{cases} x = t + x_0 \\ y = \frac{1}{t+x_0} + y_0 - \frac{1}{x_0} \end{cases}$$

$$\gamma^u(t) = \varphi_t \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = \begin{pmatrix} t+x_0 \\ \frac{1}{t+x_0} + y_0 - \frac{1}{x_0} \end{pmatrix}$$

$$\varphi_0 \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

$$\varphi_{t+t'} = \varphi_t \circ \varphi_{t'}$$

1-parameter groups of M

$$\mathbb{R} \times M \ni (t, p) \xrightarrow{\text{smooth}} \varphi_t(p) \in M$$

1° $\varphi_0 = \text{id}$

2° $\varphi_t \circ \varphi_{t'} = \varphi_{t+t'}$

local 1-parameter groups of M

$$\forall p \in U_p, \varepsilon > 0$$

$$]-\varepsilon, \varepsilon[\times U_p \ni (t, p) \rightarrow \varphi_t(p) \in M$$

1° as above for $|t|, |t'|, |t+t'| < \varepsilon$

← this only holds locally.
If t and t' are too far from 0 the second component blows up.

Def

$t \rightarrow \gamma(t)$ is called an integral curve of X passing through p if $\gamma(0) = p$,

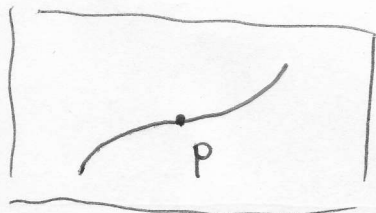
↑
differentiable

$$\frac{d\gamma}{dt} = X_{\gamma(t)}$$

$\leadsto$ locally

$$\frac{d\gamma}{dt} = X^u(\gamma(t)) \text{ where } X = X^u(x^u) \frac{\partial}{\partial x^u}$$

unique theory of autonomous systems governs.



There exist $\varepsilon > 0$ and a unique curve

$$] -\varepsilon, \varepsilon[\ni t \mapsto \gamma(t) = \varphi(t, p) = \varphi_t(p)$$

$$\text{s.t. } \gamma(0) = p \text{ and } \frac{d\gamma}{dt} = X_{\gamma(t)}.$$

Moreover there exists a neighbourhood $U_p \subset M$

s.t.

$$\varphi_t: U_p \rightarrow U_p \text{ for } t \in]-\varepsilon, \varepsilon[$$

~~then~~

if $t \in]-\varepsilon, \varepsilon[$ then $\varphi_t: p \rightarrow \varphi_t(p)$ is diffeomorphism with the properties

1) $\varphi_0 = \text{id}$

2) $\varphi_{t+t'} = \varphi_t \circ \varphi_{t'}$

when $t, t' \in]-\varepsilon, \varepsilon[$.

φ_t is called a flow of X

of course $X \in \mathfrak{X}(M)$ then the map

$$X: \mathcal{F}(M) \rightarrow \mathcal{F}(M) \text{ is}$$

1) linear

2) satisfies $X(f \cdot g) = X(f) \cdot g + f \cdot X(g)$

③ Commutator

$$\mathfrak{X}(M) \times \mathfrak{X}(M) \ni (X, Y) \mapsto [X, Y] \in \mathfrak{X}(M)$$

$$[X, Y](f) = X(Y(f)) - Y(X(f))$$

obviously $[X, Y]: \mathcal{F}(M) \rightarrow \mathcal{F}(M)$ and is linear

but also $[X, Y](f \cdot g) = [X, Y](f) \cdot g + f [X, Y](g)$ check!

• locally

$$X = X^\mu \partial_\mu, \quad Y = Y^\nu \partial_\nu$$

$$[X, Y] = (X^\mu Y^\nu_{,\mu} - Y^\nu X^\mu_{,\mu}) \partial_\nu$$

• properties

1° $[,]$ - bilinear

2° $[X, Y] = -[Y, X]$ antisymmetric

3° $[X, [Y, Z]] + [Z, [X, Y]] + [Y, [Z, X]] = 0$,
Jacobi.

$(\mathfrak{X}(M), [,])$ Lie algebra of smooth vector fields
over M (infinite dim).

④ (Vector) distribution

Def ~~###~~ An m -dimensional distribution S on M is a map

$$M \ni p \xrightarrow{S} S_p \subset T_p(M)$$

$\uparrow$
 m -dimensional (vector) subspace of $T_p(M)$

if $\forall p \in M \exists U_p \exists (X_i)_{i=1, \dots, m}$ of class C^∞ s.t.
 $\forall q \in U_p (X_i|_q)$ is a basis for $S_q \Rightarrow S_q$ is smooth

Only SMOOTH distributions from now on.

- $X \in S \Leftrightarrow \forall p \ X_p \in S_p$
- S is involutive $\Leftrightarrow X, Y \in S \Rightarrow [X, Y] \in S$
- M_S is an integral manifold of S iff
 - M_S is a submanifold of M s.t.

$$\forall p \in M_S \quad T_p(M_S) = S_p$$

Note Vector field is a distribution of dim 1.
 Its integral manifolds $\cong$ integral curves.

What about existence of integral manifolds ~~for~~
 for $m > 1$ dimensional
 distributions?

⑤ Frobenius theorem

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$$(S \text{ is involutive}) \Leftrightarrow \left(\begin{array}{l} \text{through every point } p \in M \\ \text{passes precisely one} \\ \text{(maximal) integral manifold} \\ M_S \text{ of } S \end{array} \right)$$

in such a case

$\forall p \in M \exists (U, \alpha) \text{ s.t. } p \in U \text{ and } \text{intersections of}$
 $\text{all } E_S \cap U \text{ are given}$
 by $x^{m+1}, x^{m+2}, \dots, x^n = \text{const.}$



then

$$X_i = A_i^j(x^n) \frac{\partial}{\partial x^j} \quad j=1, \dots, m$$

is a local basis in S

Fact

X_i on U linearly independent vector fields.

$$[X_i, X_j] = 0 \quad \forall i, j = 1, \dots, m \Leftrightarrow \text{there exists a coordinate system } x^\mu \text{ in } V \subset U$$

s.t. $X_i = \frac{\partial}{\partial x^i}$
 $i=1, \dots, m.$

⑥ Tensors.

$$n < \infty$$

V - n -dimensional vector space over $\mathbb{K} = \mathbb{R}, \mathbb{C}$

$$V^* = \{ \omega: V \xrightarrow{\text{linear}} \mathbb{K} \}$$

$$V_s^r = \underbrace{V \otimes \dots \otimes V}_r \otimes \underbrace{V^* \otimes \dots \otimes V^*}_s =$$

$$= L(\underbrace{V^*, \dots, V^*}_r, \underbrace{V, \dots, V}_s; \mathbb{R})$$

↑
multilinear maps from $V^* \times V^* \times \dots \times V^* \times V \times \dots \times V \rightarrow \mathbb{R}$.

$\{e_\mu\}$ - basis in V

$$\mu = 1, \dots, n$$

$\{e^\mu\}$ - dual basis in V^* defined by

$$\mu = 1, \dots, n$$

$$e^\mu(e_\nu) = \delta^\mu_\nu$$

$$V \ni v = v^\mu e_\mu; \quad \omega = \omega_\mu e^\mu \in V^*$$

Basis in V_s^r :

$e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes e^{\nu_1} \otimes \dots \otimes e^{\nu_s}$ defined by

$$(e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes e^{\nu_1} \otimes \dots \otimes e^{\nu_s})(e^{\alpha_1}, \dots, e^{\alpha_r}, e_{\beta_1}, \dots, e_{\beta_s}) =$$

$$= \delta_{\mu_1}^{\alpha_1} \dots \delta_{\mu_r}^{\alpha_r} \delta_{\beta_1}^{\nu_1} \dots \delta_{\beta_s}^{\nu_s}$$

$$V_s^r \ni K = K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes e^{\nu_1} \otimes \dots \otimes e^{\nu_s}$$

Contraction $C_j^i: V_s^r \xrightarrow{\text{linear}} V_{s-1}^{r-1}$

$$\begin{matrix} 1 \leq i \leq r \\ 1 \leq j \leq s \end{matrix}$$

$$C_j^i(v_1 \otimes \dots \otimes v_r \otimes \omega^1 \otimes \dots \otimes \omega^s) = \underbrace{\delta^i_j}_{\downarrow} v_1 \otimes \dots \otimes v_r \otimes \omega^1 \otimes \dots \otimes \omega^s$$

⑦ Change of the basis

$$\boxed{e'^{\mu} = a^{\mu}_{\nu} e^{\nu}} \quad e' = a e$$

$$a = (a^{\mu}_{\nu}) \in GL(n, K)$$

$$e'_{\mu} = e_{\nu} b^{\nu}_{\mu}$$

$$e'^{\mu}(e'_{\nu}) = a^{\mu}_{\sigma} b^{\sigma}_{\nu} e^{\sigma}(e_{\sigma}) = a^{\mu}_{\sigma} b^{\sigma}_{\nu} \delta^{\sigma}_{\sigma} \\ \Rightarrow a \cdot b = 1 \Rightarrow b = a^{-1}$$

$$\boxed{e'_{\mu} = e_{\nu} a^{-1 \nu}_{\mu}}$$

$$v = v^{\mu} e_{\mu} = v'^{\mu} e'_{\mu} = v'^{\mu} e_{\nu} a^{-1 \nu}_{\mu}$$

$$\Rightarrow v^{\nu} = v'^{\mu} a^{-1 \nu}_{\mu} \Rightarrow \boxed{v'^{\mu} = a^{\mu}_{\nu} v^{\nu}}$$

$$\omega = \omega_{\mu} e^{\mu} = \omega'_{\mu} a^{\mu}_{\nu} e^{\nu}$$

$$\Rightarrow \omega_{\mu} = \omega'_{\nu} a^{\mu}_{\nu} \Rightarrow \boxed{\omega'_{\mu} = \omega_{\nu} a^{-1 \nu}_{\mu}}$$

$$K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} \mapsto a^{\mu_1}_{\alpha_1} \dots a^{\mu_r}_{\alpha_r} K^{\alpha_1 \dots \alpha_r}_{\beta_1 \dots \beta_s} a^{-1 \beta_1}_{\nu_1} \dots a^{-1 \beta_s}_{\nu_s} \\ = K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}$$

~~old style definition of tensor:~~

$$T = P(V) \otimes \dots \otimes P(V) \otimes \dots \otimes P(V)$$

vector space

Old style view on tensors

$$K \sim (e, K^{\alpha_1 \dots \alpha_r}_{\beta_1 \dots \beta_s})$$

$$e \mapsto e' = e a^{-1}$$

$$K^{\alpha_1 \dots \alpha_r}_{\beta_1 \dots \beta_s} \mapsto K'^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}$$

How to introduce a vector space structure on side pairs?

⑧ Objects of type S.

$g: G \xrightarrow{\text{hom}} GL(W)$ i.e. g is a representation of G in W .
vector space of $\dim W = N < \infty$

$a \in G$; $W \ni w \xrightarrow{g(a)} g(a)w \in W$ is a left action of G on W .

~~$g(1) = \text{id}$~~ • $g(1) = \text{id}$

• ~~$g(a \cdot b) = g(a)g(b)$~~

V another vector space; $P(V)$ set of all basis in V
of $\dim V = n < \infty$

$G = GL(V)$ naturally acts on $P(V)$:

$$P(V) \ni e = (e_\mu) \xrightarrow{a \in GL(V)} e' = e \cdot a^{-1}$$

$$e'_\mu = e_\nu a^{-1}{}^\nu_\mu$$

now in

$$P(V) \times W \ni (e, w) \xrightarrow{\varphi_a} \varphi_a(e, w) = (e a^{-1}, g(a)w)$$

this is a left action of $GL(V)$ on $P(V) \times W$

$$(e, w) \sim (e', w') \iff \exists a \in GL(n, \mathbb{R}) \text{ s.t.}$$

$$(e', w') = \varphi_a(e, w)$$

this is an equivalence relation in $P(V) \times W$.

check!

$$W_g = P(V) \times W / \sim$$

↑
space of
objects of
type S

One can introduce a structure of ^(a)vector
space in W_g

$$[(e, w)], [(e', w')] \sim [(e, \tilde{w})]$$

$$\alpha [(e, w)] + \beta [(e', w')] = [(e, \alpha w + \beta \tilde{w})]$$

Check
that this
does not
depend on
the choice
of representatives

$$\left. \begin{array}{l} \dim W_g \\ \parallel \\ \dim W \end{array} \right\}$$

Examples

① $W = \mathbb{R}^{n(r+s)}, \quad V = \mathbb{R}^n,$

$$g(a) K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} = a^{\mu_1}_{\alpha_1} \dots a^{\mu_r}_{\alpha_r} K^{\alpha_1 \dots \alpha_r}_{\beta_1 \dots \beta_s} a^{-1\beta_1}_{\nu_1} \dots a^{-1\beta_s}_{\nu_s}$$

$$W_g = V_s^r \text{ tensors of type } \binom{r}{s} = g_s^r(a) K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}$$

② $W = \mathbb{R}^{n(r+s)}, \quad V = \mathbb{R}^n$

$$g(a) = (\det a)^w g_s^r(a)$$

W_g - tensor densities of weight w .

e.g. **[A]** Levi-Civita symbol defined by a) b) c):

a) $\epsilon_{\mu_1 \dots \mu_n} = \epsilon[\mu_1 \dots \mu_n]$; b) $\epsilon_{1 \dots n} = 1$

c) $\epsilon'_{\mu_1 \dots \mu_n} = \epsilon_{\mu_1 \dots \mu_n}$
 $\uparrow$
 totally skew symmetric in n indices

$$a^{-1\mu_1}_{\nu_1} \dots a^{-1\mu_n}_{\nu_n} \epsilon_{\mu_1 \dots \mu_n} = (\det a)^{-1} \epsilon_{\nu_1 \dots \nu_n} =$$

$$= (\det a)^{-1} \epsilon'_{\nu_1 \dots \nu_n}$$

$$\Rightarrow \epsilon'_{\nu_1 \dots \nu_n} = (\det a) g_n(a) \epsilon_{\mu_1 \dots \mu_n}$$

~~density~~ density of covariant n -tensor of weight $+1$.

[B] $\det(g_{\mu\nu})$

$$\det(g'_{\mu\nu}) = (\det a)^{-2} \det(g_{\mu\nu})$$

scalar density of weight -2

[C] $W = \mathbb{R}^{n(r+s)}, \quad g(a) = \operatorname{sgn}(\det a) g_s^r(a)$

e.g. W_g - pseudotensors

$$\eta_{\mu_1 \dots \mu_n} = \sqrt{|\det g|} \epsilon_{\mu_1 \dots \mu_n}$$

Tensor fields

$$T_p(M) \cong T_p(M)^n$$

$$M \ni p \longrightarrow K_p \in T_p(M)^n$$

locally (U, x) :

$$K = K^{u_1 \dots u_r}_{v_1 \dots v_s} \frac{\partial}{\partial x^{u_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{u_r}} \otimes dx^{v_1} \otimes \dots \otimes dx^{v_s}$$

$\uparrow$
smooth $\implies K$ is smooth

$\mathcal{X}(M)^r_s$ - module of ^{smooth} tensor fields on M over $\mathcal{F}(M)$
vector space of smooth tensor fields on M over $K = \mathbb{R}, \mathbb{C}$.

$$\mathcal{X}(M)^0_0 = \mathcal{F}(M)$$

$$\mathcal{T}(M) = \left(\bigoplus_{r=0}^{\infty} \bigoplus_{s=0}^{\infty} \mathcal{X}(M)^r_s, \otimes \right)$$

algebra of _{smooth} tensor fields over M .